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6	0	6,125,198.pn. and sub-regions	USPAT; US-PGPUB;	2004/08/16 11:37
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- 8 stereo adj vision and interface\$6 and USPAT; 2004/08/12	
computer and camera\$1 and first and EPO; JPO;	
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image\$1 and detect\$9 and object\$1 and IBM_TDB	
intersect\$6 - 8 stereo adj vision and interface\$6 and USPAT; 2004/08/12	
application adj program and run\$9 and US-PGPUB; 09:46	
computer and camera\$1 and first and EPO; JPO;	
second and arrange\$6 and configurat\$6 and DERWENT;	
image\$1 and detect\$9 and object\$1 and IBM_TDB intersect\$6 and field\$1 and view\$1	
8 stereo adj vision and interface\$6 and USPAT; 2004/08/12	
application adj program and run\$9 and US-PGPUB; 09:47	
computer and camera\$1 and first and EPO; JPO;	
second and arrange\$6 and configurat\$6 and DERWENT;	
image\$1 and detect\$9 and object\$1 and IBM_TDB intersect\$6 and field\$1 and view\$1 and	
depth\$1 and range\$1	
- 8 stereo adj vision and interface\$6 and USPAT; 2004/08/12	
application adj program and run\$9 and US-PGPUB; 09:47	
computer and camera\$1 and first and EPO; JPO;	
second and arrange\$6 and configurat\$6 and DERWENT; image\$1 and detect\$9 and object\$1 and IBM TDB	
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depth\$1 and range\$1 and user	

-	8	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and	US-PGPUB;	09:47
		computer and camera\$1 and first and	EPO; JPO;	
		second and arrange\$6 and configurat\$6 and	DERWENT;	
į		image\$1 and detect\$9 and object\$1 and	IBM_TDB	
1		intersect\$6 and field\$1 and view\$1 and		
		depth\$1 and range\$1 and user and select\$6		
-	8	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and	US-PGPUB;	09:48
		computer and camera\$1 and first and	EPO; JPO;	
		second and arrange\$6 and configurat\$6 and	DERWENT;	
		image\$1 and detect\$9 and object\$1 and	IBM_TDB	
		intersect\$6 and field\$1 and view\$1 and	_	
		depth\$1 and range\$1 and user and select\$6		
		AND CONTROL\$6		
-	8	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and	US-PGPUB;	09:48
		computer and camera\$1 and first and	EPO; JPO;	
		second and arrange\$6 and configurat\$6 and	DERWENT;	
		image\$1 and detect\$9 and object\$1 and	IBM_TDB	
		intersect\$6 and field\$1 and view\$1 and	_	
		depth\$1 and range\$1 and user and select\$6		
		AND CONTROL\$6 and region\$1		
-	0	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
}		application adj program and run\$9 and	US-PGPUB;	09:49
		computer and camera\$1 and first and	EPO; JPO;	
	l	second and arrange\$6 and configurat\$6 and	DERWENT;	
		image\$1 and detect\$9 and object\$1 and	IBM TDB	
		intersect\$6 and field\$1 and view\$1 and	_	
		depth\$1 and range\$1 and user and select\$6		
		and objetc and interset\$6 AND CONTROL\$6		
		and region\$1		
-	0	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and	US-PGPUB;	09:49
		computer and camera\$1 and first and	EPO; JPO;	
		second and arrange\$6 and configurat\$6 and	DERWENT;	
İ		image\$1 and detect\$9 and object\$1 and	IBM_TDB	
		intersect\$6 and field\$1 and view\$1 and		
2		depth\$1 and range\$1 and user and select\$6		
		and object and interset\$6 AND CONTROL\$6		
ļ		and region\$1		
- !	8	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
.		application adj program and run\$9 and	US-PGPUB;	10:23
ļ		computer and camera\$1 and first and	EPO; JPO;	
į.		second and arrange\$6 and configurat\$6 and	DERWENT;	
ŀ		image\$1 and detect\$9 and object\$1 and	IBM_TDB	
		intersect\$6 and field\$1 and view\$1 and	-	
		depth\$1 and range\$1 and user and select\$6		
		and object and interest\$6 AND CONTROL\$6		
		and region\$1		
- !	7	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
į.		application adj program and run\$9 and	US-PGPUB;	09:51
İ		computer and camera\$1 and first and	EPO; JPO;	
		second and arrange\$6 and configurat\$6 and	DERWENT;	
ł		image\$1 and detect\$9 and object\$1 and	IBM TDB	
		intersect\$6 and field\$1 and view\$1 and	-	
		depth\$1 and range\$1 and user and select\$6		
ļ		and object and interest\$6 AND CONTROL\$6		
1		and region\$1 and position\$6 and location		
	ľ	and search and point and interest		

-	0	stered adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and	US-PGPUB;	09:52
		computer and camera\$1 and first and	EPO; JPO;	
	į	second and arrange\$6 and configurat\$6 and	DERWENT;	
		image\$1 and detect\$9 and object\$1 and	IBM_TDB	i
		intersect\$6 and field\$1 and view\$1 and		
		depth\$1 and range\$1 and user and select\$6		
		and object and interest\$6 AND CONTROL\$6		l
		and region\$1 and position\$6 and location		
		and search and point and interest and		
		close\$6 and map and position and		
		coordinate\$1 and position and indiactor		
-	4	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and	US-PGPUB;	09:53
		computer and camera \$1 and first and	EPO; JPO;	
		second and arrange\$6 and configurat\$6 and	DERWENT;	
		image\$1 and detect\$9 and object\$1 and	IBM_TDB	
		intersect\$6 and field\$1 and view\$1 and		
		depth\$1 and range\$1 and user and select\$6		
		and object and interest\$6 AND CONTROL\$6		
		and region\$1 and position\$6 and location		
l i		and search and point and interest and		
		close\$6 and map and position and		
		coordinate\$1 and position and indicator	HCDATE:	2004/09/12
-	8	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
	1	application adj program and run\$9 and	US-PGPUB;	10:12
		computer and camera\$1 and first and	EPO; JPO;	
		second and arrange\$6 and configurat\$6 and	DERWENT;	
		image\$1 and detect\$9 and object\$1 and	IBM_TDB	
		intersect\$6 and field\$1 and view\$1 and		
		depth\$1 and range\$1 and user and select\$6		
		and object and interest\$6 AND CONTROL\$6 and region\$1 and position\$6 and location		
_	13		USPAT;	2004/08/13
_	13	application adj program and run\$9 and	US-PGPUB;	12:45
		computer and camera\$1 and first and	EPO; JPO;	12.45
		second and arrange\$6	DERWENT;	
		Second and arrange vo	IBM TDB	
_ *	1	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
	•	application adj program and run\$9 and	US-PGPUB;	10:24
		computer and camera\$1 and first and	EPO; JPO;	1 10.21
		second and arrange\$6 and configurat\$6 and	DERWENT;	
		image\$1 and detect\$9 and object\$1 and	IBM TDB	
		intersect\$6 and field\$1 and view\$1 and		1
		depth\$1 and range\$1 and user and select\$6		1
		and object and interest\$6 AND CONTROL\$6		
	[and region\$1 and sub adj region\$1		
-	1		USPAT;	2004/08/12
	[application adj program and run\$9 and	US-PGPUB;	10:24
	[computer and camera\$1 and first and	EPO; JPO;]
		second and arrange\$6 and sub adj region\$1	DERWENT;	
]		IBM TDB	
_	1	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
]	application adj program and run\$9 and	US-PGPUB;	10:25
	[computer and camera\$1 and first and	EPO; JPO;	
		second and sub adj region\$1	DERWENT;	
			IBM TDB	
-	3	stereo adj vision and interface\$6 and	USPAT;	2004/08/12
		application adj program and run\$9 and	US-PGPUB;	10:25
		computer and camera\$1 and first and	EPO; JPO;	
	[second and divide\$9 adj region\$1	DERWENT;	
			IBM TDB	
-	2	"20040046736"	USPAT;	2004/08/16
			US-PGPUB;	08:17
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
		The state of the s		

-	1	"2004-046736" and stereo and vision	USPAT;	2004/08/12
			US-PGPUB; EPO; JPO;	14:43
			DERWENT;	
			IBM TDB	
-	1	"20040046736" and capture\$6 and image	USPAT;	2004/08/12
			US-PGPUB;	15:04
			EPO; JPO; DERWENT;	
			IBM TDB	
_	1	"20040046736" and processing and image	USPAT;	2004/08/12
			US-PGPUB;	14:59
			EPO; JPO;	
			DERWENT; IBM TDB	
_	1	"20040046736" and processing and image	USPAT;	2004/08/12
		and user	US-PGPUB;	14:59
			EPO; JPO;	
}			DERWENT; IBM TDB	
_	1	"20040046736" and capture\$6 and image and	USPAT;	2004/08/12
		process\$6 and user	US-PGPUB;	15:05
		; -	EPO; JPO;	
			DERWENT;	
_	1	"20040046736" and capture\$6 and image and	IBM_TDB USPAT;	2004/08/12
-		process\$6 and user and stereo and vision	US-PGPUB;	15:49
		F	EPO; JPO;	
			DERWENT;	
		, , , , , , , , , , , , , , , , , , ,	IBM_TDB	0004/00/10
-	0	"20040046736" and capture\$6 and image and process\$6 and user and stereo and vision	USPAT; US-PGPUB;	2004/08/12 15:50
		and map and coordinate\$1	EPO; JPO;	13.30
		and map and coordinate;	DERWENT;	
			IBM_TDB	
-	1	"20040046736" and capture\$6 and image and process\$6 and user and stereo and vision	USPAT; US-PGPUB;	2004/08/12
		and coordinate\$1	EPO; JPO;	16.06
ء ا		s s s s s s s s s s s s s s s s s s s	DERWENT;	
		•	IBM_TDB	
-	1	"20040046736" and reference	USPAT;	2004/08/12
			US-PGPUB; EPO; JPO;	16:06
,			DERWENT;	
[.			IBM_TDB	
-	1	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
			US-PGPUB; EPO; JPO;	10:49
1			DERWENT;	
			IBM_TDB	
-	0		USPAT;	2004/08/12
		reference	US-PGPUB; EPO; JPO;	16:09
			DERWENT;	
			IBM_TDB	
-	0	"20040046736" and compare\$6 and	USPĀT;	2004/08/12
		reference adj camera	US-PGPUB;	16:09
			EPO; JPO; DERWENT;	
1			IBM TDB	
-	3	6,720,949	USPAT;	2004/08/12
			US-PGPUB;	16:11
			EPO; JPO;	
			DERWENT; IBM TDB	
_	3	6,720,949.pn.	USPAT;	2004/08/12
1		, · · , - · · · E	US-PGPUB;	16:11
			EPO; JPO;	
			DERWENT;	
L	L	<u> </u>	IBM_TDB	

-	0	6,720,949.pn. and reference adj camera	USPAT;	2004/08/12
			US-PGPUB;	16:11
			EPO; JPO;	
			DERWENT;	
			IBM TDB	
-	1	6,720,949.pn. and two adj cameras	USPĀT;	2004/08/12
			US-PGPUB;	16:11
1			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	0	6,720,949.pn. and two adj cameras and	USPAT;	2004/08/12
		compare\$6 adj images	US-PGPUB;	16:12
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	0		USPAT;	2004/08/12
		compare\$6 adj images	US-PGPUB;	16:12
			EPO; JPO;	İ
			DERWENT;	
	_	5 017 027	IBM_TDB	2004/02/12
-	2	5,917,937.pn.	USPAT;	2004/08/12
			US-PGPUB;	16:13
			EPO; JPO;	
			DERWENT;	
		E 017 027 mm and have add	IBM_TDB	2004/00/12
-	0		USPAT;	2004/08/12
		compare\$6 adj images	US-PGPUB;	16:14
			EPO; JPO;	
			DERWENT; IBM TDB	
_	_	5,917,937.pn. and cameras and compare\$6	USPAT;	2004/08/12
-	١	adj images	US-PGPUB;	16:14
		auj images	EPO; JPO;	10.14
			DERWENT;	
			IBM TDB	
_	n	5,917,937.pn. and two adj cameras and	USPAT;	2004/08/12
		compare\$6 and images	US-PGPUB;	16:14
		compared and images	EPO; JPO;	20021
		z.	DERWENT;	
	1		IBM TDB	
-	1	5,917,937.pn. and cameras and compare\$6	USPAT;	2004/08/12
	1	and images	US-PGPUB;	16:14
		·	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	2	5,917,937.pn.	USPAT;	2004/08/13
			US-PGPUB;	07:06
			EPO; JPO;	
			DERWENT;	
		5 017 027 mm and accommends	IBM_TDB	2004/00/12
[-	1	5,917,937.pn. and compare\$6	USPAT;	2004/08/13
	1		US-PGPUB;	07:06
			EPO; JPO;	
			DERWENT; IBM TDB	
_	19	stereo adj vision and reference adj	USPAT;	2004/08/13
	19	camera	US-PGPUB;	07:13
	}	Camera	EPO; JPO;	07.13
			DERWENT;	
			IBM TDB	
_	14	stereo adj vision and reference adj	USPAT;	2004/08/13
	**	camera and feature\$1 and pair\$1	US-PGPUB;	15:35
			EPO; JPO;	
			DERWENT;	
			IBM TDB	
_	1	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
[[anD PAIR	US-PGPUB;	12:09
			EPO; JPO;	
			DERWENT;	
1			IBM_TDB	
		**************************************		····

-	1	"200 46736" and reference and compares	USPAT;	2004/08/13
		and Park and lifter	US-PGPUB; EPO; JPO;	12:58
			DERWENT;	
1			IBM TDB	:
-	4		USPAT;	2004/08/13
		camera and feature\$1 and pair\$1 and	US-PGPUB;	15:32
		filter	EPO; JPO;	
			DERWENT; IBM TDB	
_	0	stereo adj vision and interface\$6 and	USPAT;	2004/08/13
		application adj program and run\$9 and	US-PGPUB;	12:44
		computer and camera\$1 and first and	EPO; JPO;	
		second and arrange\$6 and two adj cameras	DERWENT;	
		and compare\$6 adj images	IBM_TDB	0004/00/12
-	0	stereo adj vision and interface\$6 and	USPAT;	2004/08/13
		application adj program and run\$9 and computer and camera\$1 and first and	US-PGPUB; EPO; JPO;	12:44
		second and arrange\$6 and two adj cameras	DERWENT;	
		and compare\$6 adj images	IBM_TDB	
-	3	stereo adj vision and interface\$6 and	USPAT;	2004/08/13
		application adj program and run\$9 and	US-PGPUB;	12:47
		computer and camera\$1 and first and	EPO; JPO;	
		second and arrange\$6 and reference and compare\$6 anD PAIR and filter\$1 and	DERWENT; IBM TDB	
		capture\$6 and image and capture\$6 and	1211_122	
•		image and process\$6 and user and stereo		
		and vision and coordinate\$1		
-	0	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
		anD PAIR and filter and calculate and match and score and rank	US-PGPUB; EPO; JPO;	12:59
		match and score and rank	DERWENT;	
			IBM TDB	
-	1	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
		anD PAIR and filter and calculate and	US-PGPUB;	13:35
		match and score	EPO; JPO;	
			DERWENT; IBM TDB	
_ *	l o	stereo adj vision and reference adj'	USPAT;	2004/08/13
		camera and feature\$1 and pair\$1 and	US-PGPUB;	13:35
		filterand and reference and compare\$6 anD	EPO; JPO;	
		PAIR and filter and calculate and match	DERWENT;	
		and score and eliminate	IBM_TDB	2004/09/12
I -	1	"20040046736" and reference and compare\$6 anD PAIR and filter and calculate and	USPAT; US-PGPUB;	2004/08/13 13:36
		match and score and eliminate	EPO; JPO;	13.30
			DERWENT;	
			IBM_TDB	
-	1	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
		anD PAIR and filter and calculate and match and score and eliminate and	US-PGPUB;	13:42
		feature\$1	EPO; JPO; DERWENT;	
		Toucatoyi	IBM_TDB	
-	1	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
		anD PAIR and filter and calculate and	US-PGPUB;	14:17
		match and score and eliminate and	EPO; JPO;	
		feature\$1 and threshold	DERWENT;	
_	1	"20040046736" and reference and compare\$6	IBM_TDB USPAT;	2004/08/15
		anD PAIR and filter and calculate and	US-PGPUB;	14:32
		match and score and eliminate and	EPO; JPO;	
		feature\$1 and threshold and scene and	DERWENT;	
		coordinate	IBM_TDB	
-	0	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
		anD PAIR and filter and calculate and match and score and eliminate and	US-PGPUB; EPO; JPO;	14:21
		feature\$1 and threshold and scene and	DERWENT;	
1]	coordinate and divide\$9 and block\$1	IBM TDB	
L	L	The state of the s		

[-	0	"20040046736" and reference and compare\$	USPAT;	2004/08/13
		anD PAIR and filter and calculate and	US-PGPUB;	14:22
		match and score and eliminate and	EPO; JPO;	
		feature\$1 and threshold and scene and	DERWENT;	
ļ		coordinate and divide\$9	IBM_TDB	
-	0	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
		anD PAIR and filter and calculate and	US-PGPUB;	14:22
		match and score and eliminate and	EPO; JPO;	
		feature\$1 and threshold and scene and	DERWENT;	
		coordinate and (divide\$9 or split\$9) and	IBM_TDB	
		block\$1	HCDND.	2004/09/12
-	0	"20040046736" and reference and compare\$6 anD PAIR and filter and calculate and	USPAT; US-PGPUB;	2004/08/13 14:22
		match and score and eliminate and	EPO; JPO;	14.22
		feature\$1 and threshold and scene and	DERWENT;	
		coordinate and (divide\$9 or split\$9 OR	IBM TDB	
	1	DIFFERENTIALE) and block\$1	15155	
_	l o	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
		anD PAIR and filter and calculate and	US-PGPUB;	14:23
		match and score and eliminate and	EPO; JPO;	
		feature\$1 and threshold and scene and	DERWENT;	
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		differentiate) and block\$1		
-	1	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
		anD PAIR and filter and calculate and	US-PGPUB;	15:02
	[match and score and eliminate and	EPO; JPO;	
		feature\$1 and threshold and scene and coordinate and block\$1	DERWENT;	
1_	0	coordinate and block\$1 5,159,159.pn	<pre>IBM_TDB USPAT;</pre>	2004/08/13
		3,139,139.pii	US-PGPUB;	14:29
			EPO; JPO;	1
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_	1	5,159,159.pn. and horizontal	USPAT;	2004/08/13
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			EPO; JPO;	
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Ţ -	0	5,159,159.pn. and horizontal and synch	USPAT;	2004/08/13
			US-PGPUB;	14:29
			EPO; JPO; DERWENT;	
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_	0	5,159,159.pn. and horizontal and synch\$9	USPAT;	2004/08/13
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-	1	5,159,159.pn. and horizontal	USPAT;	2004/08/13
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1_	0	"20040046736" and mafarance and same^	IBM_TDB	2004/08/13
[-]	"20040046736" and reference and compare\$6 anD PAIR and filter and calculate and	USPAT; US-PGPUB;	15:02
	1	match and score and eliminate and	EPO; JPO;	10.02
		feature\$1 and threshold and scene and	DERWENT;	
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-	0	"20040046736" and reference and compare\$6	USPAT;	2004/08/13
1		anD PAIR and filter and calculate and	US-PGPUB;	15:02
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1-	0	"20040046736" and reference and compare\$6 anD PAIR and filter and calculate and	USPAT; US-PGPUB;	2004/08/13 15:03
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TBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; IS:37 EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; IS:38 EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; IS:38 EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; IS:38 EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JP					
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- 0 stereo adj vision and matrix and pixel\$1 USPAT; USPGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-FGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-FGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-FGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; USPGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; USPGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-FGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-FGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-FGPUB; EPO; JPO; DERWENT; ISM_TDB USPAT; US-FGPUB; EPO; JPO; DERWENT; US-FGPUB; EPO; JPO; DERWENT; US-FGPUB; EPO; JPO; DERWENT;]			13.30
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and "8x8" - 12 stereo adj vision and reference adj camera and matrix and pixel\$1 - 1 "20040046736" and matrix - 241 stereo adj vision and display and pixel\$1 1	-	0	stereo adj vision and matrix and pixel\$1		2004/08/13
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- 12 stereo adj vision and reference adj camera and matrix and pixel\$1 USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT;				DERWENT;	
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DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT;	1		camera and matrix and pixel\$1		15:39
- 241 stereo adj vision and display and pixel\$1	1]			
- 241 stereo adj vision and display and pixel\$1 USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; US-PGPUB; EPO; JPO; DERWENT;	1	}			
- 241 stereo adj vision and display and pixel\$1 US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; DERWENT;			#2004004C72C#		2004/00/12
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DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; DERWENT; DERWENT; DERWENT;					13:40
- 241 stereo adj vision and display and pixel\$1 USPAT; US-PGPUB; EPO; JPO; DERWENT;	1				
- 241 stereo adj vision and display and pixel\$1 USPAT; 2004/08/13 US-PGPUB; EPO; JPO; DERWENT;	1	[
US-PGPUB; 15:42 EPO; JPO; DERWENT;	_	241	stereo adi vision and display and nivels1		2004/08/13
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DERWENT;					<u>-</u>
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_	4	steree adj vision and display and pixels and active adj matrix	USPAT; US-PGPUB; EPO; JPO;	2004/08/13 15:45
_	0	stereo adj vision and display and pixel\$1	DERWENT; IBM_TDB USPAT;	2004/08/13
		and active adj matrix and "8x8"	US-PGPUB; EPO; JPO; DERWENT; IBM TDB	15:45
_	9	stereo adj vision and display and pixel\$1 adj block	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/13 15:46
-	1	"20040046736" and reference and compare\$6 anD PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and pixel\$1 and pattern and contrast and compare	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:05
_	0	"20040046736" and reference and compare\$6 anD PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and pixel\$1 and pattern and contrast and compare and cluster\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 12:33
-	2	6,125,198.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 11:36
_	2	6,661,918.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/14 12:54
-	1	6,661,918.pn. and cluster\$1 and image\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/14 12:56
-	1	6,661,918.pn. and cluster\$1 and image\$1 and compare and position	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/14 13:04
-	0	6,661,918.pn. and cluster\$1 and image\$1 and compare and position and coordinate\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/14 13:04
_	1	6,661,918.pn. and cluster\$1 and image\$1 and compare and position	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 11:36
_	1	"20040046736" and reference and compare\$6 anD PAIR and filter and calculate and match and score and eliminate and feature\$1 and threshold and scene and coordinate and block\$1 and pixel\$1 and pattern and contrast and compare and features	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/14 13:32

-	0	6,125,198.pn. and threshold and	USPAT;	2004/08/14
		calculat\$9 and match\$9 and feature\$1 and	US-PGPUB;	13:13
		pairs and disparity and select\$9 and	EPO; JPO;	
		highest and pixel\$1 and divi\$9 and	DERWENT;	
		block\$1 and image\$1 and reference and	IBM_TDB	
		camera\$1 and compare\$8 and create\$9 and		
	.	image\$1 and cluster\$1 and threshold	HCD2m.	2004/00/14
-	1	6,661,918.pn. and cluster\$1 and image\$1	USPAT;	2004/08/14 13:13
		and compare and position and threshold	US-PGPUB;	13:13
			EPO; JPO; DERWENT;	
			IBM TDB	
1_	1	6,661,918.pn. and cluster\$1 and image\$1	USPAT;	2004/08/15
	1	and compare and position and threshold	US-PGPUB;	14:16
		and eliminate	EPO; JPO;	14.10
			DERWENT;	
			IBM TDB	
] _	1	"20040046736" and head\$1	USPAT;	2004/08/14
	_		US-PGPUB;	13:43
			EPO; JPO;	
			DERWENT;	
İ			IBM_TDB	
-	1	"20040046736" and head\$1 and smooth\$6	USPAT;	2004/08/14
1			US-PGPUB;	13:38
1			EPO; JPO;	
1			DERWENT;	
	_		IBM_TDB	
-	0	6,125,198.pn. and threshold and	USPAT;	2004/08/14
		calculat\$9 and match\$9 and feature\$1 and	US-PGPUB;	13:38
		pairs and disparity and select\$9 and	EPO; JPO;	
		highest and pixel\$1 and divi\$9 and	DERWENT;	
1		block\$1 and image\$1 and reference and	IBM_TDB	
		<pre>camera\$1 and compare\$8 and create\$9 and image\$1 and cluster\$1</pre>		
_	1	"20040046736" and head\$1 and smooth\$6 and	USPAT;	2004/08/14
		image and frames	USPAT; US-PGPUB;	13:41
		Image and Italies	EPO; JPO;	13.41
			DERWENT;	
		\$	IBM TDB	ء
<u>-</u>	1	"20040046736" and head\$1 and smooth\$6 and	USPAT;	2004/08/14
	_	frames	US-PGPUB;	13:41
			EPO; JPO;	
		·	DERWENT;	
			IBM_TDB	
-	0	"20040046736" and hand\$1 and orient\$6 and	USPĀT;	2004/08/14
		calulat\$6 and informat\$6 and object\$1 and	US-PGPUB;	13:45
		posit\$6	EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	1	"20040046736" and hand\$1 and orient\$6 and	USPAT;	2004/08/14
		calculat\$6 and informat\$6 and object\$1	US-PGPUB;	13:49
		and posit\$6	EPO; JPO;	
			DERWENT;	
		#20040046726# and hand61 and add and a	IBM_TDB	2004/09/15
-	1	"20040046736" and hand\$1 and orient\$6 and	USPAT;	2004/08/15
		<pre>calculat\$6 and informat\$6 and object\$1 and posit\$6 and coordinate\$6</pre>	US-PGPUB;	16:15
		and bosiese and coordinatese	EPO; JPO;	
			DERWENT; IBM TDB	
_	2	"20040046736" and computer	USPAT;	2004/08/14
		20010030700 and compater	US-PGPUB;	14:16
			EPO; JPO;	1
			DERWENT;	
			IBM TDB	
_	1	"20040046736" and computer and interface	USPAT;	2004/08/14
	*	20010010.00 wild compaced did interrace	US-PGPUB;	14:23
1			EPO; JPO;	
			DERWENT;	
			IBM TDB	
	1			

	"2003-046736" and capture\$6 and image\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/16 11:32
	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature\$1 and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and image\$1 and reference and camera\$1 and compare\$8 and create\$9 and	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 13:46
-	image\$1 and cluster\$1 6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature\$1 and pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and image\$1 and reference and camera\$1 and compare\$8 and create\$9 and image\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 14:17
	stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 and object and interest\$6 AND CONTROL\$6 and region\$1 and position\$6 and location and search and point and interest and close\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15
	6,661,918.pn. and map\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:33
-	6,125,198.pn. and map\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 14:18
	"20040046736" and map\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 14:17
-	"20040046736" and mapp\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 14:18
	"20040046736" and map	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 14:18
	6,125,198.pn. and map	USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/15 16:26
- :	"20040046736" and stereo adj image and stereo adj camera	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/15 14:58
- ("20040046736" and x-axis	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 14:58

-	1	"200-5046736" and x and axis	USPAT;	2004/08/15
			US-PGPUB;	15:00
			EPO; JPO;	
			DERWENT;	
		#2004004C72C# and # and and a and band01	IBM_TDB	2004/09/15
_	1	"20040046736" and x and axis and hand\$1	USPAT;	2004/08/15 15:33
			US-PGPUB; EPO; JPO;	13.33
			DERWENT;	
			IBM TDB	
<u>-</u> .	1	"20040046736" and X and axis and Z	USPAT;	2004/08/15
			US-PGPUB;	15:34
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	1	"20040046736" and X and axis and Z and	USPAT;	2004/08/15
		depth	US-PGPUB;	15:35
			EPO; JPO;	
			DERWENT; IBM TDB	
_	1	"20040046736" and (storage or stor\$6) and	USPAT;	2004/08/15
		orient\$6 and posit\$6 and coordinate\$6	US-PGPUB;	16:25
			EPO; JPO;	
			DERWENT;	
			IBM_TDB	
-	0	"20040046736" and avatar	USPAT;	2004/08/15
			US-PGPUB;	16:29
			EPO; JPO;	[
			DERWENT;	
_	0	6 125 198 nn and avatan	IBM_TDB	2004/08/15
-		6,125,198.pn. and avatar	USPAT; US-PGPUB;	16:26
			EPO; JPO;	10.20
			DERWENT;	İ
			IBM TDB	
-	0	6,661,918.pn. and avatar	USPAT;	2004/08/15
			US-PGPUB;	16:33
		٠.	EPO; JPO;	ء
		•	DERWENT;	•
	2	-t add addition and interestance and	IBM_TDB	2004/08/15
-	2	stereo adj vision and interface\$6 and application adj program and run\$9 and	USPAT; US-PGPUB;	16:27
		computer and camera\$1 and first and	EPO; JPO;	10.27
		second and avatar	DERWENT;	
]		· · · · · · · · · · · · · · · · · · ·	IBM TDB	
-	2	stereo adj vision and interface\$6 and	USPAT;	2004/08/15
		application adj program and run\$9 and	US-PGPUB;	16:28
[computer and camera\$1 and avatar	EPO; JPO;	
			DERWENT;	
	a	stores add trigion and indicates of and	IBM_TDB	2004/09/15
-	1	stereo adj vision and indicator\$1 and avatar	USPAT; US-PGPUB;	2004/08/15 16:28
		avacar	EPO; JPO;	10.20
1			DERWENT;	
			IBM TDB	
-	8	stereo adj vision and avatar	USPAT;	2004/08/15
		-	US-PGPUB;	16:36
			EPO; JPO;	
			DERWENT;	
		#00040046736# 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	IBM_TDB	2004/00/25
-	1	"20040046736" and animation	USPAT;	2004/08/15
			US-PGPUB;	16:30
			EPO; JPO; DERWENT;	
			IBM TDB	[
_	0	"20040046736" and animation and facial	USPAT;	2004/08/15
		and sens\$6	US-PGPUB;	16:30
		•	EPO; JPO;	·
			DERWENT;	
			IBM_TDB	

-	1	"200-046736" and animation and face and sens\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/15 16:30
	0	6,661,918.pn. and animation	IBM_TDB USPAT;	2004/08/15
	Ū	o, ooi, 510.pm. and animacion	US-PGPUB; EPO; JPO; DERWENT;	16:33
	0	6,661,918.pn. and animation	IBM_TDB USPAT;	2004/08/15
			US-PGPUB; EPO; JPO; DERWENT;	16:33
-	8	stereo adj vision and avatar and indicat\$6	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/15 16:38
_	2	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and application adj program and run\$9 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:39
_	7	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:39
_	2	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and application adj program and run\$9 and computer	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/15 16:39
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:43
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:41
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and depth\$1 and user and select\$6 AND CONTROL\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:41
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and arrange\$6 and configurat\$6 and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/15 16:42

_	3	ster adj vision and avatar and	USPAT;	2004/08/15
		indicat\$6 and stereo adj vision and	US-PGPUB;	16:42
	,	interface\$6 and computer and camera\$1 and	EPO; JPO;	
		first and second and arrange\$6 and	DERWENT;	
		configurat \$6 and image \$1 and detect \$9 and	IBM_TDB	
İ		object\$1 and view\$1 and user and		
	9	select\$6 AND CONTROL\$6	HCDAT.	2004/08/15
-	3	stereo adj vision and avatar and indicat\$6 and stereo adj vision and	USPAT; US-PGPUB;	16:42
		interface\$6 and computer and camera\$1 and	EPO; JPO;	10.42
		first and second and arrange\$6 and	DERWENT;	
		configurat\$6 and image\$1 and detect\$9 and	IBM TDB	
}		object\$1 and user and select\$6 AND		
		CONTROL\$6		
 -	3	stereo adj vision and avatar and	USPAT;	2004/08/15
		indicat\$6 and stereo adj vision and	US-PGPUB;	16:42
		interface\$6 and computer and camera\$1 and	EPO; JPO;	
		first and second and arrange\$6 and	DERWENT;	
		configurat \$6 and image \$1 and detect \$9 and	IBM_TDB	
	ا ا	object\$1 and user and select\$6	******	2004/00/15
-	3	· •	USPAT;	2004/08/15
	1	indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and	US-PGPUB; EPO; JPO;	16:42
		arrange\$6 and configurat\$6 and image\$1	DERWENT;	
		and detect\$9 and object\$1 and user and	IBM TDB	
		select\$6	15155	
_	7	stereo adj vision and avatar and	USPAT;	2004/08/15
		indicat\$6 and stereo adj vision and	US-PGPUB;	16:43
		interface\$6 and computer and camera\$1 and	EPO; JPO;	
		image\$1 and detect\$9 and object\$1 and	DERWENT;	
	_	user and select\$6	IBM_TDB	
-	3	stereo adj vision and avatar and	USPAT;	2004/08/15
		indicat\$6 and stereo adj vision and	US-PGPUB;	16:43
		interface\$6 and computer and camera\$1 and	EPO; JPO;	
		first and second and image\$1 and detect\$9 and object\$1 and intersect\$6 and field\$1	DERWENT; IBM TDB	
		and view\$1 and depth\$1 and range\$1 and	IBM_IDB	
		user and select\$6 AND CONTROL\$6 and		
		region\$1		ا ء
-	7	stereo adj vision and avatar and	USPAT;	2004/08/15
		indicat\$6 and stereo adj vision and	US-PGPUB;	16:43
		interface\$6 and computer and camera\$1 and	EPO; JPO;	
	i .	first and second	DERWENT;	
	_		IBM_TDB	2004/00/15
-	7	stereo adj vision and avatar and	USPAT;	2004/08/15
		<pre>indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and</pre>	US-PGPUB; EPO; JPO;	16:44
		first and second and image\$1 and detect\$9	DERWENT;	
		and object\$1	IBM TDB	
-	4	stereo adj vision and avatar and	USPAT;	2004/08/15
		indicat\$6 and stereo adj vision and	US-PGPUB;	16:45
		interface\$6 and computer and camera\$1 and	EPO; JPO;	
		first and second and image\$1 and detect\$9	DERWENT;	
		and object\$1 and intersect\$6 and field\$1	IBM_TDB	
ļ	_	and view\$1		
-	7	stereo adj vision and avatar and	USPAT;	2004/08/15
]		indicat\$6 and stereo adj vision and	US-PGPUB;	16:45
]	interface\$6 and computer and camera\$1 and	EPO; JPO;	
		first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1	DERWENT;	
_	7	and object; and fleid; and view; stereo adj vision and avatar and	IBM_TDB USPAT;	2004/08/15
	'	indicat\$6 and stereo adj vision and	US-PGPUB;	16:45
		interface\$6 and computer and camera\$1 and	EPO; JPO;	10.30
		first and second and image\$1 and detect\$9	DERWENT;	
		and object\$1 and field\$1 and view\$1 and	IBM TDB	
		depth\$1 and range\$1	-	
			· · · · · · · · · · · · · · · · · · ·	·

indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and depth\$1 and range\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 - 2 "20010033675" USPAT; USPAT; USPEWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; J	/08/16 7
interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 "20010033675" 1 "20010033675" 1 "20010033675" and map 2 "20010033675" and map 3 stereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and map\$6 2 "20040046736" and mouse 1 "20010033675" and virtual 3 "20010033675" and virtual 4 "20010033675" and virtual 5 EPO; JPO; DERWENT; IBM TDB 5 EPO; JPO; DERWENT; IBM TDB 6 IBM TDB 8 EPO; JPO; DERWENT; IBM TDB 8 EPO; JPO; DERWENT; IBM TDB 8 EPO; JPO; DERWENT; IBM TDB 9 EPO; JPO; DERWENT; IBM TDB 1 "20010033675" and virtual	,
first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 stereo adj vision and avatar and interface\$6 and computer and camera\$1 and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 2 "20010033675" 1 "20010033675" 1 "20010033675" and map 3 tereo adj vision and avatar and indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 indicat\$6 and stereo adj vision and interface\$6 and computer and camera\$1 indicat\$6 and stereo adj vision and depth\$1 and range\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and depth\$1 and range\$1 and user and select\$6 AND CONTROL\$6 and region\$1 and coordinate\$1 and map\$6 2 "20040046736" and mouse 1 "20010033675" and virtual 1 "20010033675" and virtual 2 "20040046736" and virtual 3 "20010033675" and virtual 4 "20010033675" and virtual 5 perwent; 1 percepub; 2 pe	
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_	1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and object\$1 and user and select\$6 and coordinate\$1 and virtual and hands and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:04
-	1	stereo adj vision and avatar and stereo adj vision and computer and camera\$1 and image\$1 and object\$1 and user and virtual and hands and velocity and roam and virtual and environment and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:05

	1 stell adj vision and avatar and computer and camera\$1 and image\$1 and object\$1 and user and virtual and hands and velocity and roam and virtual and environment and application and program	USPAT; 2004/08/16 US-PGPUB; 09:05 EPO; JPO; DERWENT; IBM TDB
_	stereo adj vision and avatar and object\$1 and user and virtual and hands and velocity and roam and virtual and environment and application and program	USPAT; 2004/08/16 US-PGPUB; 09:05 EPO; JPO; DERWENT;
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-	stereo adj vision and avatar and virtual and velocity and roam and virtual and environment and application and program	USPAT; 2004/08/16 US-PGPUB; 09:05 EPO; JPO; DERWENT; IBM TDB
-	stereo adj vision and avatar and virtual and velocity and roam and virtual and environment	USPAT; 2004/08/16 US-PGPUB; 09:06 EPO; JPO; DERWENT; IBM TDB
-	1 stereo adj vision and avatar and virtual and velocity and roam and environment	USPAT; 2004/08/16 US-PGPUB; 09:06 EPO; JPO; DERWENT; IBM TDB
-	4 avatar and virtual and velocity and roam and environment	USPAT; 2004/08/16 US-PGPUB; 09:19 EPO; JPO; DERWENT; IBM TDB
-	avatar and virtual and velocity and roam and environment and hand	USPAT; 2004/08/16 US-PGPUB; 09:20 EPO; JPO; DERWENT; IBM TDB
-	avatar and virtual and velocity and roam and environment and hand\$1 and stereo adj vision	USPAT; 2004/08/16 US-PGPUB; 09:20 EPO; JPO; DERWENT; IBM TDB
-	avatar and virtual and velocity and roam and environment and hand\$1 and interface\$6 and computer and camera\$1	USPAT; 2004/08/16 US-PGPUB; 09:21 EPO; JPO; DERWENT; IBM TDB
-	2 avatar and virtual and velocity and roam and environment and hand\$1 and computer and camera\$1	USPAT; 2004/08/16 US-PGPUB; 09:21 EPO; JPO; DERWENT; IBM TDB
-	3 avatar and virtual and velocity and roam and environment and hand\$1 and computer	USPAT; 2004/08/16 US-PGPUB; 09:21 EPO; JPO; DERWENT; IBM TDB

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-	2	avatar and virtual and velocity and roam and environment and hand\$1 and computer and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and velocity and function and applied and avatar and roam and virtual and environment	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:24
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-	3	avatar and virtual and velocity and roam and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:27
_	2	avatar and virtual and velocity and roam and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and camera\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:27
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-	1	avatar and virtual and velocity and roam and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and neutral and object and selected and function and applied and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:29

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-	2	ave r and virtual and velocity and roam and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and object and selected and program and application and function and applied and application and program	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:30
-	2	avatar and virtual and velocity and roam and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and object and selected and plect and selected and object and selected and plect and selected and function and applied	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:30
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-	2	avatar and virtual and velocity and roam and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and object\$1 and function\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:31
-	3	avatar and virtual and velocity and roam and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and selected and program and application and interface and object\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:31

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_	0	avatar and virtual and velocity and roam and environment and hand\$1 and computer and first and second and image\$1 and detect\$9 and object\$1 and field\$1 and view\$1 and user and select\$6 AND CONTROL\$6 and virtual and hands and avatar and hand and object and (un adj selected) and program and application and interface and object\$1 and apply\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/08/16 09:35
_	2	6088035.pn.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 09:45
_	1	6088035.pn. and selected	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 09:51
_	1	6088035.pn. and hand\$1	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 09:51
_	1	"20010033675" and hands	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/16 10:11

L	Hits	Search Text	DB	Time stamp
Number	2	6 125 100 mm	USPAT;	2004/08/14
1	2	6,125,198.pn.	US-PGPUB; EPO; JPO;	09:44
2	49	and match and feature and pairs and score and disparity and selecting and	DERWENT; IBM_TDB USPAT; US-PGPUB; EPO; JPO;	2004/08/14 09:46
3	0	highest 6,125,198.pn. and threshold and	DERWENT; IBM_TDB USPAT;	2004/08/14
	·	calculating and match and feature and pairs and score and disparity and selecting and highest	US-PGPUB; EPO; JPO; DERWENT; IBM TDB	09:46
4	2 ·	6,125,198.pn. and threshold	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/14 09:46
5	0	6,125,198.pn. and threshold and calculating	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/14 09:46
6	1	6,125,198.pn. and threshold and calculat\$9	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/14 09:47
7	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/14 09:47
8	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and score\$9 and disparity	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/14
9	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and selecting and highest	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/14 09:48
10	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest	USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/14
11	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and score\$9	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/14 09:48
12	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and score\$6	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT;	2004/08/14
13	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and pairs and disparity and select\$9 and highest and score\$6 and acieve\$9	IBM_TDB USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM TDB	2004/08/14 09:49

14	, 0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and	USPAT; US-PGPUB;	2004/08/14 09:49
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15	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and	USPAT; US-PGPUB;	2004/08/14 09:49
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16	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and	IBM_TDB USPAT; US-PGPUB;	2004/08/14
		pairs and disparity and select\$9 and highest	EPO; JPO; DERWENT; IBM TDB	, 65.50
17	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and	USPAT; US-PGPUB;	2004/08/14 09:56
		pairs and disparity and select\$9 and highest and pixel\$1	EPO; JPO; DERWENT; IBM TDB	
18	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and	USPAT; US-PGPUB;	2004/08/14
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19	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and	IBM_TDB USPAT; US-PGPUB;	2004/08/14
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20	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and	IBM_TDB USPAT; US-PGPUB;	2004/08/14
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21	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and	USPAT; US-PGPUB;	2004/08/14 10:00
		pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and scene\$9	EPO; JPO; DERWENT; IBM TDB	
22	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and	USPAT; US-PGPUB;	2004/08/14 10:01
		pairs and disparity and select\$9 and highest and pixel\$1 and divi\$9 and block\$1 and image\$1	EPO; JPO; DERWENT; IBM TDB	
23	0	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and	USPAT; US-PGPUB;	2004/08/14 10:02
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24	1	camera 6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and	USPAT; US-PGPUB;	2004/08/14 10:03
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25	1	6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and	USPAT; US-PGPUB;	2004/08/14 10:03
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26	1	camera and compare\$8 6,125,198.pn. and threshold and calculat\$9 and match\$9 and feature and	USPAT; US-PGPUB;	2004/08/14 10:04
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